UniRec2: 2 channels universal receiver



Main features:

- MultiFrequency: 433.42, 433.92, 434.15, 434.42, 868.3, 868.5, 868.8 MHz and other frequencies between 288 and 418MHz (only outside UE).
- Supports both AM and FM remote controls, transmitting fixed and rolling code.
- 2 relay outpus with 250Vac 5A switch capability. configurable as hold-to-run. bistable, timer from 0.5s to 1 hour, or with some special/advanced functions.
- Supports up to 60 different remote controls stored in the integrated memory; up to 1000 different remote controls when the optional memory is installed.
- You can program different types of remote control (with the same frequency and modulation) in the same receiver;
- 1 or more master remote controls can be used to enable programming of new remote controls without the need to open the box.
- Low power dissignation and consumption, due to the high efficient switching-mode power supply; works from 6 to 36Vdc, or from 7 to 27Vac.

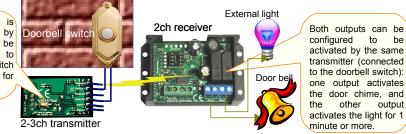
to be

output

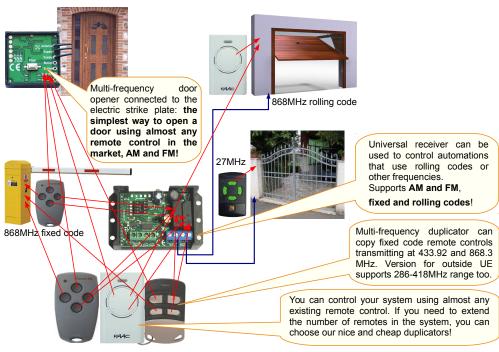
other

Wireless doorbell using the 2-ch universal receiver and one stationary transmitter

The transmitter is internally supplied by a 3V cell, so it can be easily connected to the doorbell switch without the need for external supply.



Controlling every automations, rolling code and/or working in different frequencies, using a single existing remote control.



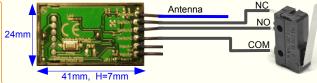
Wireless connection between safety edge and motor operator board

Relay1 configured in bistable ON/OFF, and connected to the motor operator safety input.



Door opens => NC will be shorted to COM so SenderBatt starts transmitting code #1 => UniRec2 opens Relay1 output => safety OFF => garage door cannot be opened (motor disabled).

Door closes => NO will be shorted to COM => SenderBatt starts transmitting code #2 => UniRec2 closes Relay1 output => Safety ON => garage door can be opened (motor enabled).



SenderBatt is internally supplied by a 3V battery, so it does not need for external power supply. It's very compact, so it fits anywhere.

Every time the microswitch change status, SenderBatt transmits a code used to enable or disable the output on the UniRec2 receiver. <u>Please note that this is not a 100% safety system</u>, because it's not guarantee that UniRec2 receive every command from SenderBatt (there is no feedback/acknowledge).

The 2nd relay output can be used with another SenderBatt to control another safety edge, or can be used to send open/close command to the motor operator board.

Configure output 1 on UniRec2 as Bistable ON/OFF mode:

press Prog button 1 time (channel 1), then press Prog 6 times (output mode), then press Prog 3 times (Bistable ON/OFF mode)

Program SenderBatt code#2 on Relay 1, ON mode (when door is closed, safety is ON and motor is enabled):

press *Prog* button 1 time (select channel 1), then press *Prog* 2 times (enter programming), close microswitch (*Switch2* shorted to *SwitchC*): this way SenderBatt starts transmitting code#2 and UniRec2 will learn this code to activate relay output 1.

Program SenderBatt code#1 on Relay 1, OFF mode (when door is open, safety is OFF and motor is disabled):

press *Prog* button 3 times (select channel 1, OFF mode), then press *Prog* 2 times (enter programming), open microswitch (*Switch1* shorted to *SwitchC*): this way SenderBatt starts transmitting code#1 and UniRec2 will learn this code to disactivate relay output 1.

Forward/Reverse 230Vac motor driving using UniRec2 multifrequency universal receiver

The receiver can be configured to enable only one relay output at a time; in this way **the receiver can be used to drive an async motor**: one button on the remote control will enable motor in **forward direction**, and another button will enable motor in **reverse direction**.

Two 275Vac varistors should be connected on the outputs, to preserve relay contacts from surges/sparks.

UniRec2 should be set to have both outputs configured in only one output active (parameter 7, value 4).

